

ABSTRACT

A joint of an industrial robot that includes attaching part (23) having positioning member (22) embedded in one or both of two relatively rotating members, and guide (24) through which positioning
5 member (22) projectably slides. Meanwhile, the side of the positioning member is provided thereon with a reservoir groove for a lubricant and a projection position marker for indicating a given projection length. This makeup provides an inexpensive, highly accurate, and extremely trouble-saving origin adjusting device.